16:45 Tuesday 14<sup>th</sup> April, 2015

## Math 482 Notes: Max flow and revised simplex

Let G = (V, E) be a directed graph with distinct vertices  $s, t \in V$ . Let  $P_1, \ldots, P_p$  be all of the paths from s to t in G. We define the matrix  $D = \{d_{ij}\}$  by

$$d_{ij} = \begin{cases} 1 & \text{if edge } e_i \text{ is on the path } P_j \\ 0 & \text{otherwise.} \end{cases}$$

We let  $b_i$  be the capacity on edge  $e_i$ , then the max flow LP is

$$\max \sum_{j=1}^{p} f_{j}$$
subject to 
$$Df \leq b$$

$$f \geq 0$$

Where  $Df \leq b$  is just shorthand for  $\sum_{e_i \in E} \sum_{j=1}^p d_{ij} f_j \leq b_i$  and  $f \geq 0$  is shorthand for  $f_j \geq 0$  for all  $j \in \{1, \ldots, p\}$ . We add slack variables  $s \in R^m$  to put the LP in standard form. In detail, let  $\hat{c} = [\mathbf{0^T} | \mathbf{1^T}]$ ,  $\hat{f} = \left[\frac{s}{f}\right]$ , and  $\hat{D} = [I_m | D]$ , so the LP in standard form is then:

$$\max \hat{c}^T \hat{f} \text{ s.t } \hat{D} \hat{f} \leq b, \hat{f} \geq 0.$$

Our CARRY-0 matrix is then,

$$\left| egin{array}{c|c} s_1 & 0 & \mathbf{0^T} \\ \vdots & b & I_m \\ s_m & \end{array} \right|$$

and at step  $\ell$  we have CARRY- $\ell$ 

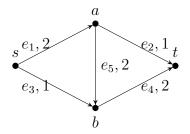
$$\hat{f}_{j_1}$$
 $\vdots$ 
 $A_B^{-1}b$ 
 $A_B^{-1}$ 

Here |f| is the current value of the flow, and  $B = \{j_1, \ldots, j_m\}$  is the current basis, (row i is solve for element  $\hat{f}_i$  and  $\hat{f}_i$  either corresponds to a slack variable or one of the s, t-paths  $P_1, \ldots, P_p$ ).

To pivot, we need  $j \in [p]$  such that  $\bar{c_j} = C_j - \pi^T D_j > 0$ , since  $c_j = 1$  for every  $j \in P$ , this is equivalent to  $\pi^T D_j < 1$ . Note that if some  $\pi_i < 0$  for some  $i \in [m]$ , then it is profitable to bring the slack variable  $s_i$  into the basis, i.e. we can pivot on row i of the CARRY matrix. We can therefore assume that  $\pi \geq 0$ .

Now we can view  $\pi_i$  as a weight/cost on edge i in the graph and find a shortest path from s, t subject to the weight/cost function  $\pi_i$ . If the cost of this path is less than 1, than it is profitable to bring  $f_i$  into the basis.

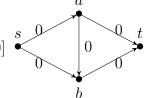
The following is an example. We start with the following directed graph (the capacities of the edges are listed after the edge labels):



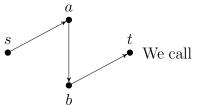
This is CARRY-0 with an additional column which will be explained later.

	0	0	0	0	0	0	1
$s_1$	2	1	0	0	0	0	(1)
$s_2$	1	0	1	0	0	0	0
$s_3$	1	0	0	1	0	0	0
$s_4$	2	0	0	0	1	0	1
$s_5$	2	0	0	0	0	1	0 0 1 1

We find the shortest s, t-path in the following graph since  $-\pi_T = [0, 0, 0, 0, 0]$ 



Every path has cost 0, so any path will work. We pick the path



this path sabt and, since it contains the edges  $e_1$ ,  $e_4$  and  $e_5$ , it corresponds to the column

$$\begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix}$$
 in  $D$ . We also have that the relative cost of the column is  $\bar{c}_j = c_j - \pi^T \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix} = 1$ 

(recall that  $c_j = 1$  for every path). We now can see how the additional column was con-

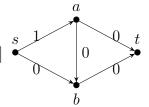
structed. It consists of 
$$A_B^{-1}$$
  $\begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}$  in rows 1 through 5 and  $\bar{c}_j = 1$  in row 0. We pivot, as we

would in normal simplex, on the circled entry.

This is CARRY-1 with the pivot column (note that we do not know what the pivot column

is until we complete the steps below, it is just listed now for convenience):  $\begin{vmatrix} -2 & -1 & 0 & 0 & 0 & 0 & 1 \\ \hline sabt & 2 & 1 & 0 & 0 & 0 & 0 & 0 \\ \hline s_2 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ \hline s_3 & 1 & 0 & 0 & 1 & 0 & 0 & 1 \\ \hline s_4 & 0 & -1 & 0 & 0 & 1 & 0 & 1 \\ \hline s_5 & 0 & -1 & 0 & 0 & 0 & 1 & 0 \\ \hline \end{cases}$ 

We find the shortest s, t-path in the following graph since  $-\pi_T = [-1, 0, 0, 0, 0]$ 



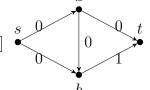
The shortest path is sbt and it has cost 0 < 1, so we bring the path into the basis. We com-

pute 
$$A_B^{-1} \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}$$
 and  $\bar{c}_j = 1 - \pi^T \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \\ 0 \end{bmatrix} = 1$ . We pivot on the circled entry.

This is CARRY-2 with an pivot column is:

	-2	0	0	0	-1	0	1	
sabt	2	1	0	0	0	0	1	
$s_2$	1	0	1	0	0	0	$(1)$	We find
$s_3$	1	1	0	1	-1	0	1	we iiiu
sbt	0	-1	0	0	1	0	-1	
$s_5$	0	-1	0	0	0	1	-1	

the shortest s, t-path in the following graph since  $-\pi_T = [0, 0, 0, -1, 0]$ 

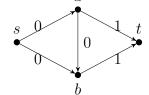


The shortest path is sat. We compute 
$$A_B^{-1}\begin{bmatrix} 1\\1\\0\\0\\0 \end{bmatrix} = \begin{bmatrix} 1\\1\\1\\-1\\-1 \end{bmatrix}$$
 and  $\bar{c}_j = 1 - \pi^T \begin{bmatrix} 1\\1\\0\\0\\0 \end{bmatrix} = 1$ .

We pivot on the circled entry.

This is CARRY-3 with an pivot column is: 
$$\begin{vmatrix} -3 & 0 & -1 & 0 & -1 & 0 \\ sabt & 1 & 1 & -1 & 0 & 0 & 0 \\ sat & 1 & 0 & 1 & 0 & 0 & 0 \\ s_3 & 0 & 1 & -1 & 1 & -1 & 0 \\ sbt & 1 & -1 & 1 & 0 & 1 & 0 \\ s_5 & 1 & -1 & 1 & 0 & 0 & 1 \end{vmatrix}$$
 We find the

shortest s, t-path in the following graph since  $-\pi_T = [0, -1, 0, -1, 0]$ 



Paths sat, sbt and sabt all have cost 1, so no path has cost less than 1. This means we are finished and the max flow is 3. This is a flow of 1 on path sabt and flow of 1 on sat and a

flow of 1 on sbt. Note that we also have one unit of slack to  $e_5$  and no slack anywhere else. We can see this by observing that  $s_5 = 1$  in the final basic feasible solution.